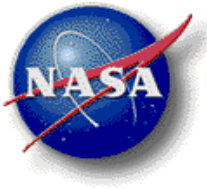


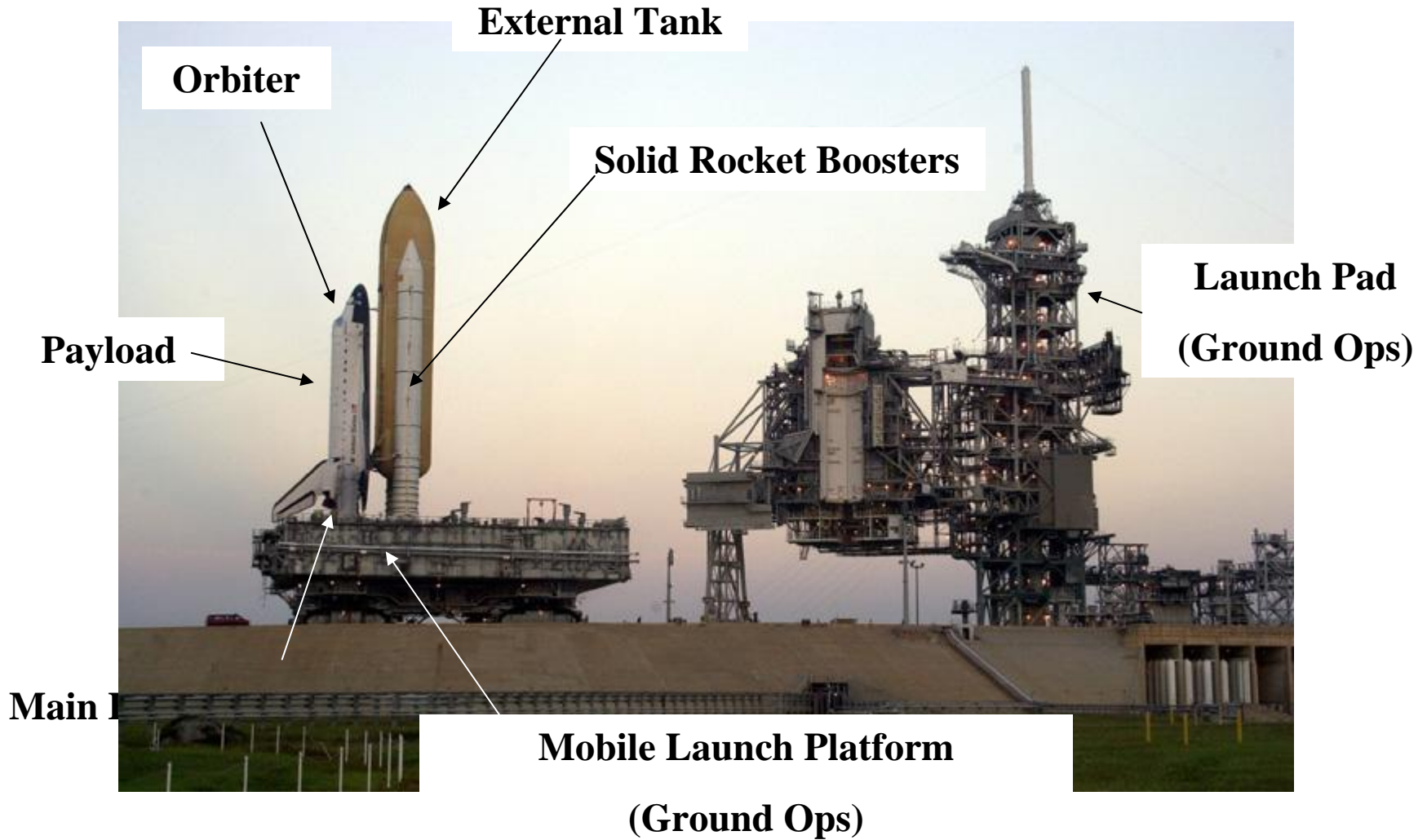
Wireless Sensor Needs in the Space Shuttle and CEV Structures Communities

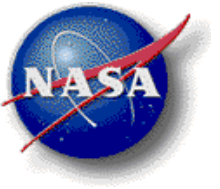
George H. James, III
Structural Engineering Division
NASA-JSC

To be presented at the CANEUS/NASA “Fly-By-Wireless” Workshop
March 27 – 28, 2007
Grapevine, TX



Space Shuttle - Hardware

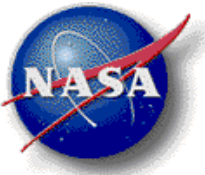




Space Shuttle - Constraints

- ❑ Mature and Aging
- ❑ Operational and Developmental
- ❑ Flexible and Robust Sensors
- ❑ Low Operational Impacts
 - Mass
 - Power
 - Storage
 - Volume
 - Safety
 - Schedule
 - **Flight-Certified**





Space Shuttle - Needs

❑ Track Fatigue Life

- Maintain Proper Level of Conservatism
- Monitor Known Loading Events

❑ Detect Impacts

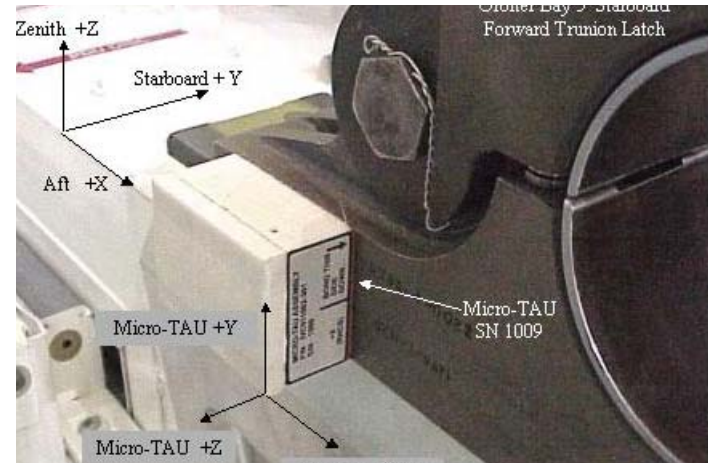
- Maintain Proper Level of Conservatism
- Monitor Unexpected Loading Events

❑ Verify Responses & Environment

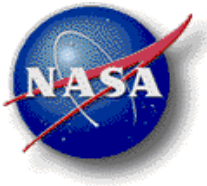
- Maintain Proper Level of Conservatism
- Allow the Implementation of New Models

❑ Continuity of Engineering Expertise

- Maintain Proper Insight into the System
- Allow Transitions between Generations



Wireless Accelerometer Package in Payload Bay

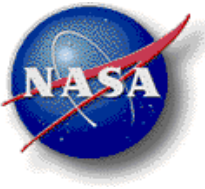


Space Shuttle – Recent Issues Summary

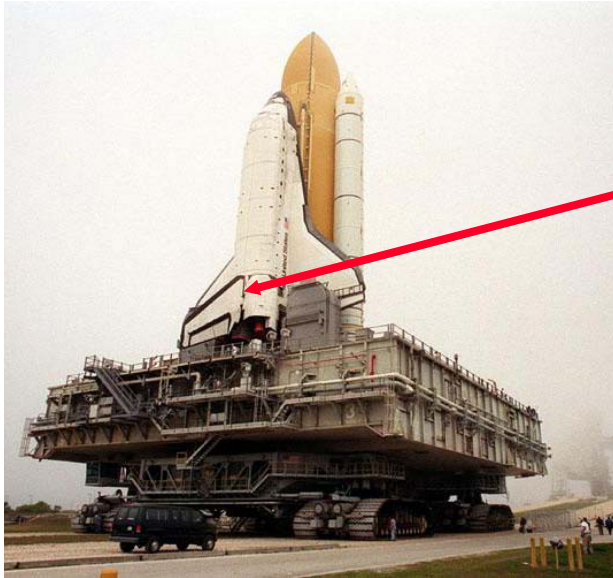
□ Issues:

- Number of Sensors
- Certification
- Integration Engineering
- Dynamic Range
- Time Synchronization
- SRB Chamber Pressures
- No ET Recorder
- Internal ET Sensors in a Small Area
- External ET Debris Hazard
- ET LOX Feedline Bracket
- Orbiter Wiring
- Orbiter TPS Change-Out

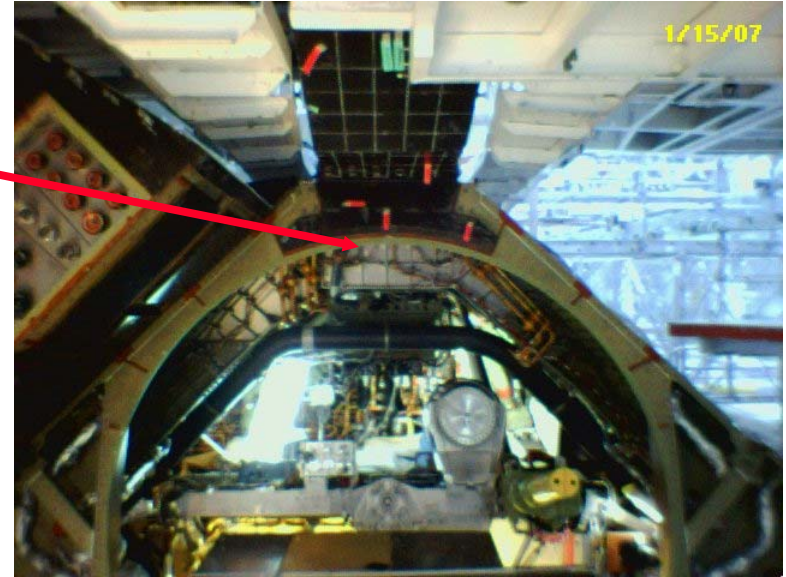




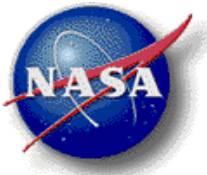
Space Shuttle – Roll-Out Example



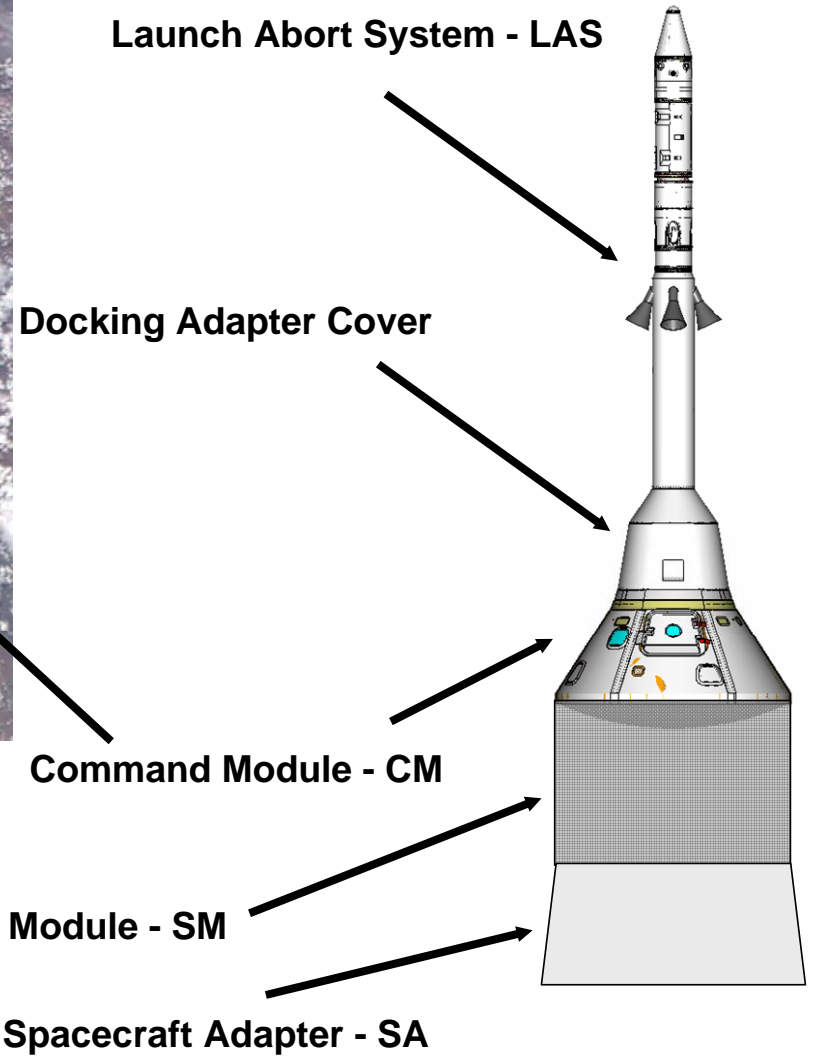
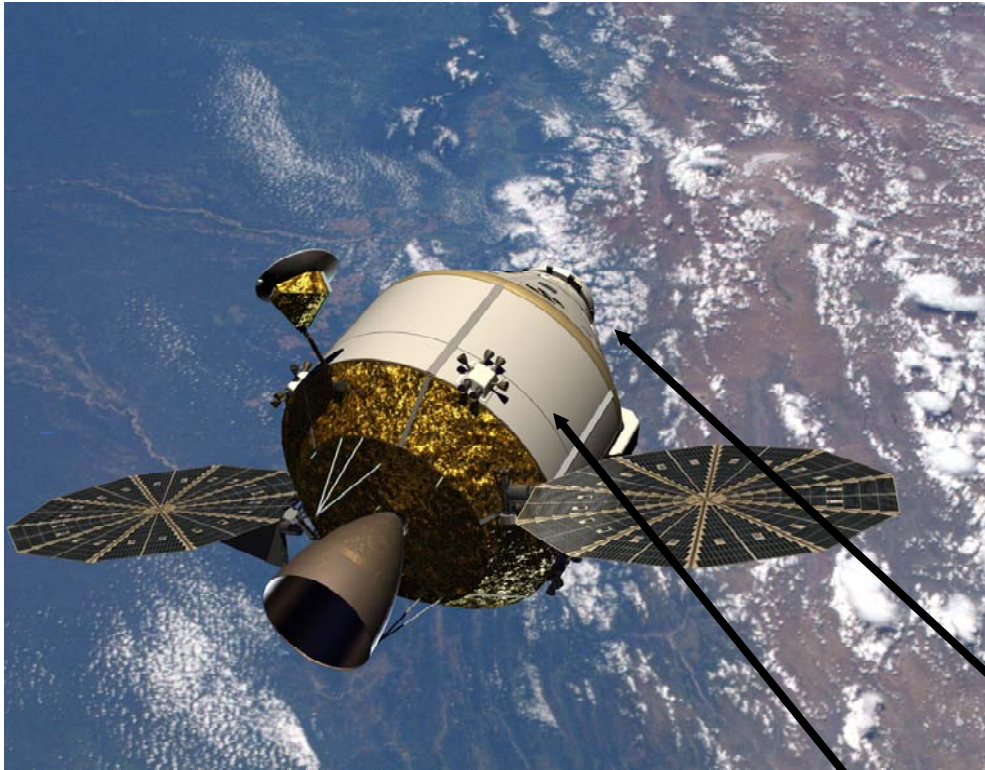
Orbiter Location

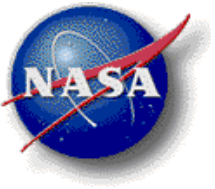


- Perform Fatigue Analysis of Roll-Out
- Temporarily Lower Speed
- Provide Minimal Instrumentation for Reconstruction
- Wired Sensors on Launch Platform and SRB's
- One Sensor Package in Orbiter
 - Must be Removed Before Flight



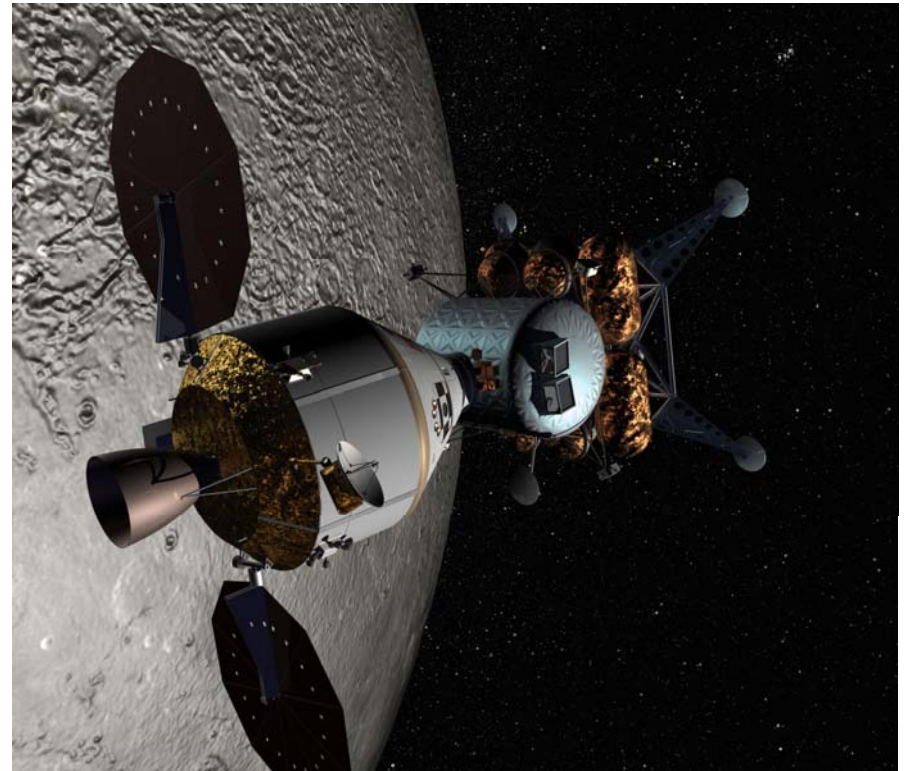
CEV - Hardware

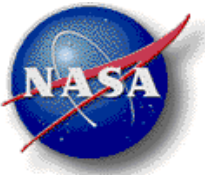




CEV - Constraints

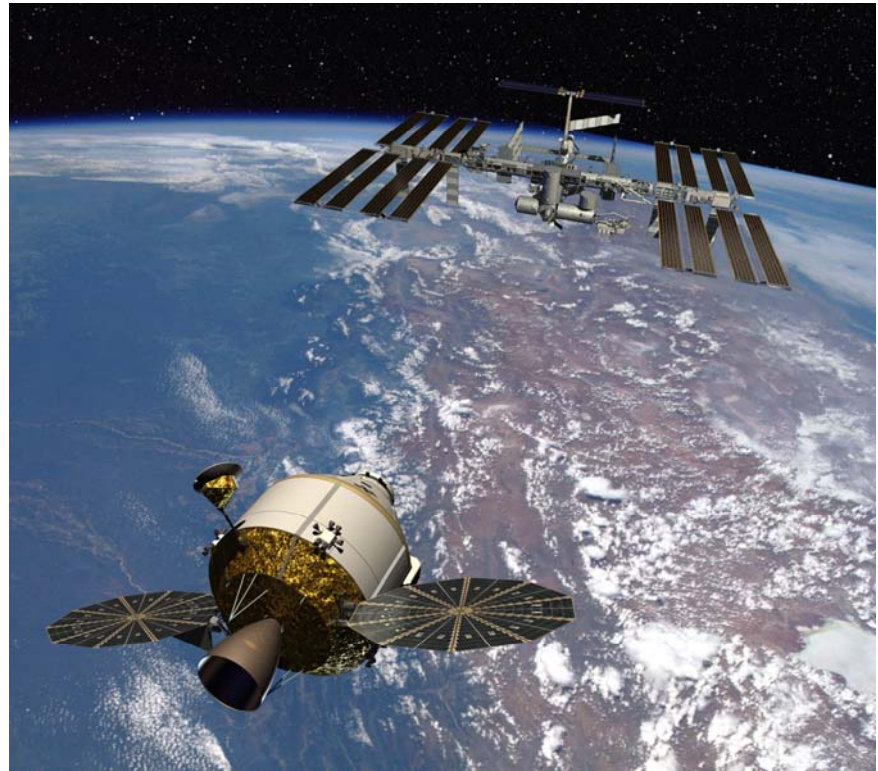
- Under Development
- Design and Mission Constantly Changing
- Large Range of Operational Missions
- Long Periods of On-Orbit Dwell
- Systems with Critical Functions
- Mass Constrained





CEV - Needs

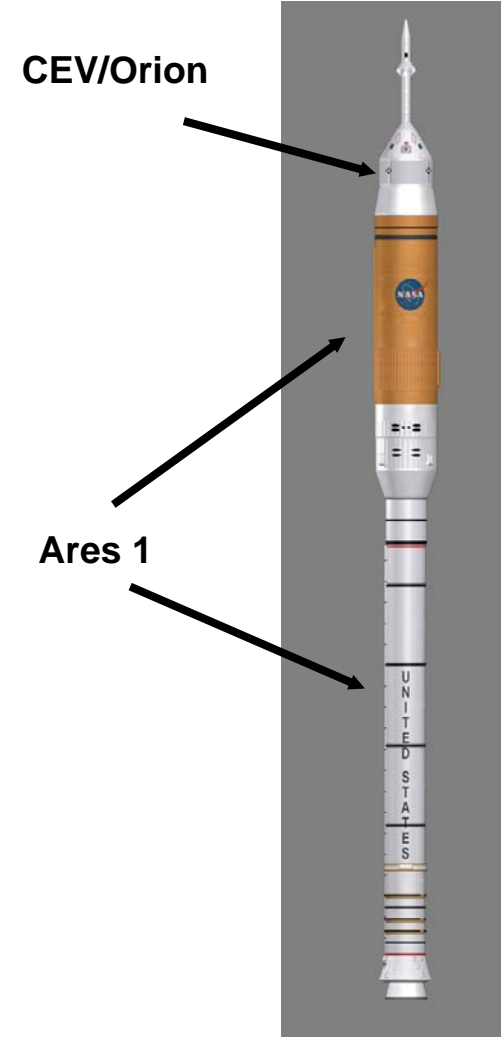
- Flexible Sensor System**
 - Adjust to New Needs
 - Rapid Implementation
- High Channel Counts**
 - Distributed Storage
 - Installation Limitations
- Mass Limited**
 - Operational Limitations
 - Early Removal
- Large Operational Range**
 - High Sample Rates
 - Large Amplitude Range
 - High Temperatures
- Off-the-Shelf Status**

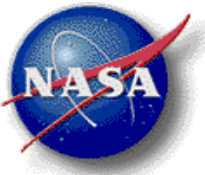




CEV – Applications

- **Ares 1X roll-out** - cannot remove wires
- **Ares 1X flight test** – increase channel count, reduce installation time (wiring)
- **Pad Abort 1 flight test** – increase channel count, reduce installation time (wiring), high temperatures
- **CEV acoustics wind tunnel test** – increase channel count, decrease wires in sting, high temperatures
- **CEV acoustics structural test** – high channel count, internal sensors
- **CEV vibration test** – high channel count, internal sensors
- **CEV modal tests** – high channel count
- **Ares/Orion modal tests (GVT)** – high channel count, reduce test costs
- **CEV operational data** – low mass/volume/power, certified



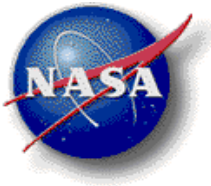


CEV – Pad Abort 1 Example

- September of 2008**
- High Channel Count**
 - > 1000 Total Desired
 - ~ 500 Total Possible
- High Sample Rates**
- High Temperatures**
- Limitations**
 - LAS is volume limited
 - 63 pounds in LAS
 - 14 Days for LAS Installation
 - 40 Days (shared) for CM Install
 - 6 Days of Pre-Flight Checkout



Apollo Pad Abort Test



Conclusions

□ Space Shuttle

- Need to control analytical conservatism
- Need to monitor unexpected impacts
- Major constraint is the need for flight certification
- Wireless systems have been successfully implemented

□ CEV

- Ground and flight needs
- Flexibility and high channel counts required
- Wired systems have proven limitations in test systems
- Major operational constraint is mass penalty